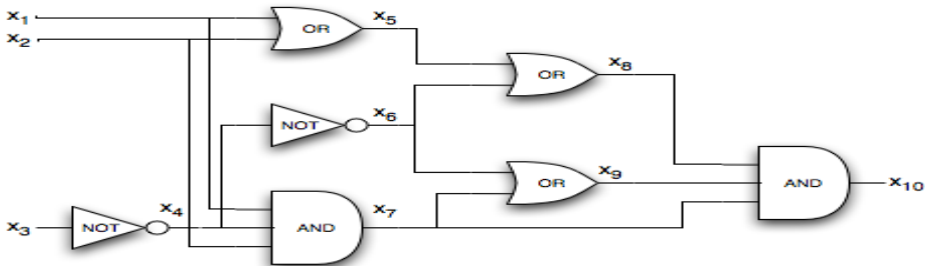


# Practical SAT Solving

Lecture 5

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- Details on implementing DPLL
  - Decision Heuristics
  - Restarts
  - Implementing Unit Propagation

- **DPLL:** Davis-Putnam-Logemann-Loveland
- **Basic idea:** case splitting (Depth first search on the partial assignments) and simplification
- **Simplification:** unit propagation and pure literal deletion
- **Unit propagation:** **1-clauses (unit clauses) fix variable values:** if  $\{x\} \in S$ , in order to satisfy  $S$ , variable  $x$  must be set to 1.
- **Pure literal deletion:** If variable  $x$  occurs only positively (or only negatively) in  $S$ , it may be fixed, i.e. set to 1 (or 0).

```
boolean DPLL(ClauseSet S)
{
  while ( S contains a unit clause {L} ) {
    delete from S clauses containing L; // unit-subsumption
    delete  $\neg L$  from all clauses in S; // unit-resolution
  }
  if (  $\perp \in S$  ) return false; // empty clause?
  while ( S contains a pure literal L )
    delete from S all clauses containing L;
  if (  $S = \emptyset$  ) return true; // no clauses?
  choose a literal L occurring in S; // case-splitting
  if ( DPLL( $S \cup \{L\}$ ) ) return true; // first branch
  else if ( DPLL( $S \cup \{\neg L\}$ ) ) return true; // second branch
  else return false;
}
```

- How can we implement unit propagation efficiently?
- How can we implement pure literal elimination efficiently?
- Which literal  $L$  to use for case splitting?
- How can we efficiently implement the case splitting step?

# “Modern” DPLL Algorithm with “Trail”

```
boolean mDPLL( ClauseSet S, PartialAssignment  $\alpha$  )
{
  while ( (S,  $\alpha$ ) contains a unit clause {L} ) {
    add {L = 1} to  $\alpha$ 
  }
  if ( a literal is assigned both 0 and 1 in  $\alpha$  ) return false;
  if ( all literals assigned ) return true;
  choose a literal L not assigned in  $\alpha$  occurring in S;
  if ( mDPLL(S,  $\alpha \cup \{L = 1\}$  ) return true;
  else if ( mDPLL(S,  $\alpha \cup \{L = 0\}$  ) return true;
  else return false;
}
```

$(S, \alpha)$ : clause set  $S$  as “seen” under partial assignment  $\alpha$

# Properties of a good decision heuristic

# Properties of a good decision heuristic

- Fast to compute
- Yields efficient sub-problems
  - More short clauses?
  - Less variables?
  - Partitioned problem?



- Best heuristic in 1992 for random SAT (in the SAT competition)
- Select the variable  $x$  with the maximal vector  $(H_1(x), H_2(x), \dots)$

$$H_i(x) = \alpha \max(h_i(x), h_i(\bar{x})) + \beta \min(h_i(x), h_i(\bar{x}))$$

- where  $h_i(x)$  is the number of unsatisfied clauses with  $i$  literals that contain the literal  $x$ .
- $\alpha$  and  $\beta$  are chosen heuristically ( $\alpha = 1$  and  $\beta = 2$ ).
- Goal: satisfy or reduce size of many preferably short clauses

- Maximum Occurrences in clauses of Minimum Size
- Popular in the mid 90s
- Choose the variable  $x$  with a maximum  $S(x)$ .

$$S(x) = (f^*(x) + f^*(\bar{x})) \times 2^k + (f^*(x) \times f^*(\bar{x}))$$

- where  $f^*(x)$  is the number of occurrences of  $x$  in the smallest unsatisfied clauses,  $k$  is a parameter
- Goal: assign variables with high occurrence in short clauses

- Considers all the clauses, shorter clauses are more important
- Choose the literal  $x$  with a maximum  $J(x)$ .

$$J(x) = \sum_{x \in c, c \in F} 2^{-|c|}$$

- Two-sided variant: choose variable  $x$  with maximum  $J(x) + J(\bar{x})$
- Goal: assign variables with high occurrence in short clauses
- Much better experimental results than Bohm and MOMS
- One-sided version works better

- (Randomized) Dynamic Largest (Combined | Individual) Sum
- Dynamic = Takes the current partial assignment in account
- Let  $C_P$  ( $C_N$ ) be the number of positive (negative) occurrences
- DLCS selects the variable with maximal  $C_P + C_N$
- DLIS selects the variable with maximal  $\max(C_P, C_N)$
- RDLCS and RDLIS does a random selection among the best
  - Decrease greediness by randomization
- Used in the famous SAT solver GRASP in 2000

- Last Encountered Free Variable
- During unit propagation save the last unassigned variable you see, if the variable is still unassigned at decision time use it otherwise choose a random
- Very fast computation: constant memory and time overhead
  - Requires 1 int variable (to store the last seen unassigned variable)
- Maintains search locality
- Works well for pigeon hole and similar formulas

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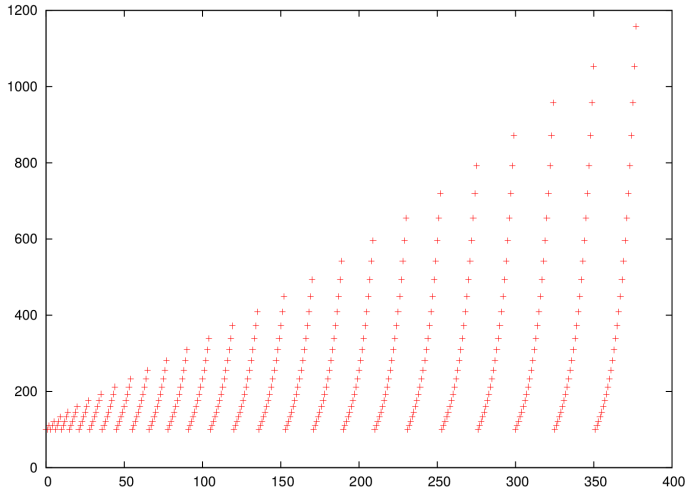


- What is a restart?
  - Clear the partial assignment
  - Unassign all the variables
  - Backtrack to level 0
- Why would anybody want to do restarts in DPLL?
  - To recover from bad branching decisions
  - You solve more instances
  - Might decrease performance on easy instances

# When to Restart?

- After a given number of decisions
- The number of decision between restarts should grow
  - To guarantee completeness
- How much increase?
  - Linear increase – too slow
  - Exponential increase – ok with small exponent
  - MiniSat:  $k$ -th restart happens after  $100 \times 1.1^k$

# Inner/Outer Restart Scheduling



## Inner/Outer Restart Algorithm

```
int inner = 100
```

```
int outer = 100
```

```
forever do
```

```
  . . . do DPLL for inner conflicts . . .
```

```
  restarts++
```

```
  if inner >= outer then
```

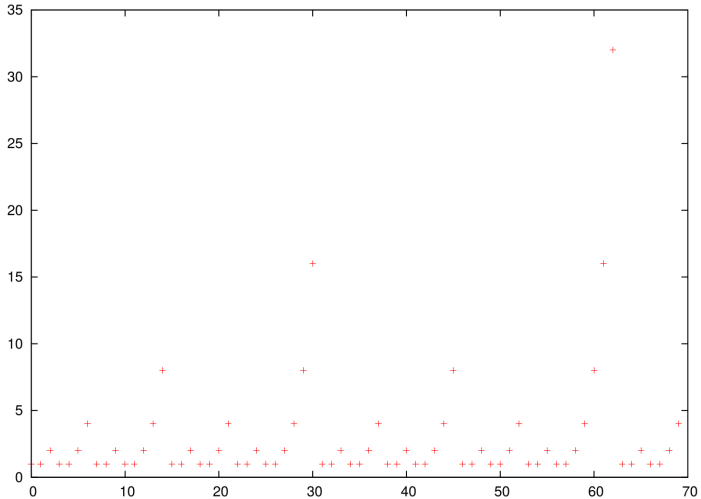
```
    outer *= 1.1
```

```
    inner = 100
```

```
  else
```

```
    inner *= 1.1
```

# Luby Sequence Restart Scheduling



## Luby Sequence Algorithm

```
unsigned luby (unsigned i)
  for (unsigned k = 1; k < 32; k++)
    if (i == (1 << k) - 1) then return 1 << (k - 1)
  for (k = 1;; k++)
    if ((1 << (k - 1)) <= i && i < (1 << k) - 1) then
      return luby(i - (1 << (k-1)) + 1);

limit = 512 * luby (++restarts);
... // run SAT core loop for limit conflicts
```

- Complicated, not trivial to compute

- A more efficient implementation of the Ruby sequence
- Use the  $v_n$  of the following pair

$$(u_1, v_1) = (1, 1) \quad (1)$$

$$(u_{n+1}, v_{n+1}) = u_n \& - u_n = v_n ? (u_n + 1, 1) : (u_n, 2v_n) \quad (2)$$

- Example: (1,1), (2,1), (2,2), (3,1), (4,1), (4,2), (4,4), (5,1), ...
- Invented by Donald Knuth

## The Task

Given a partial truth assignment  $\phi$  and a set of clauses  $F$  identify all the unit clauses, extend the partial truth assignment, repeat until fix-point.

## Simple Solution

- Check all the clauses
- Too slow
- Unit propagation cannot be efficiently parallelized (is P-complete)



## The Task

Given a partial truth assignment  $\phi$  and a set of clauses  $F$  identify all the unit clauses, extend the partial truth assignment, repeat until fix-point.

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In the context of DPLL the task is actually a bit different

- The partial truth assignment is created incrementally by adding (decision) and removing (backtracking) variable value pairs
- Using this information we will avoid looking at all the clauses

## The Real Task

We need a data structure for storing the clauses and a partial assignment  $\phi$  that can efficiently support the following operations

- detect new unit clauses when  $\phi$  is extended by  $x_i = v$
- update itself by adding  $x_i = v$  to  $\phi$
- update itself by removing  $x_i = v$  from  $\phi$
- support restarts, i.e., un-assign all variables at once

## Observation

- We only need to check clauses containing  $x_i$

## The Data Structure

- For each clause remember the number unassigned literals in it
- For each literal remember all the clauses that contain it

## Operations

- If  $x_i = T$  is the new assignment look at all the clauses in the occurrence list of  $\bar{x}_i$ . We found a unit if the clause is not SAT and counter=2
- When  $x_i = v$  is added or removed from  $\phi$  update the counters

### The Data Structure

- In each non-satisfied clause "watch" two non-false literals
- For each literal remember all the clauses where it is watched

Maintain the invariant: two watched non-false literals in non-sat clauses

- If a literal becomes false find another one to watch
- If that is not possible the clause is unit

Advantages

### The Data Structure

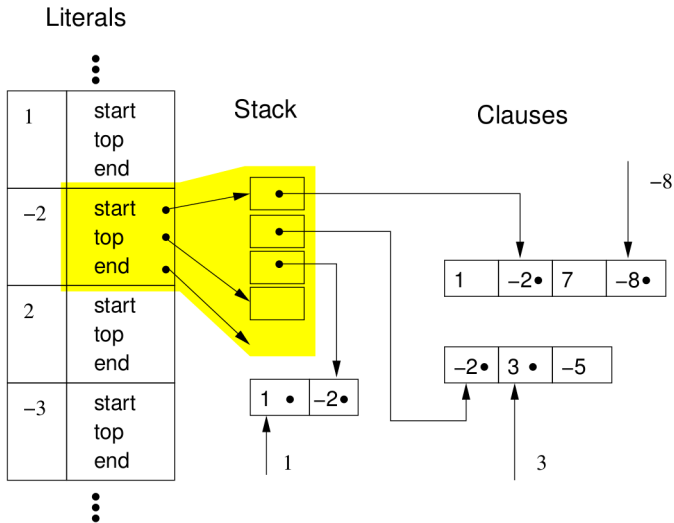
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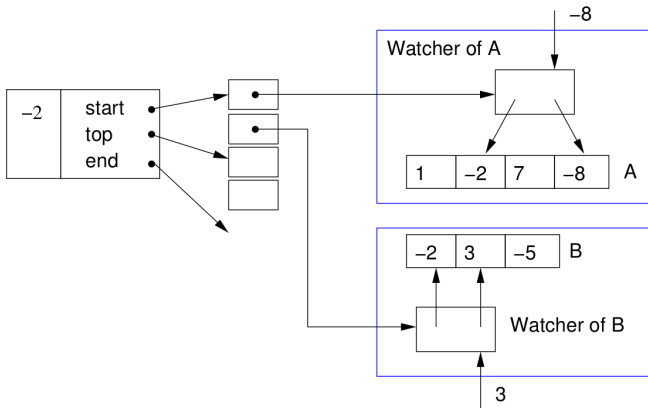
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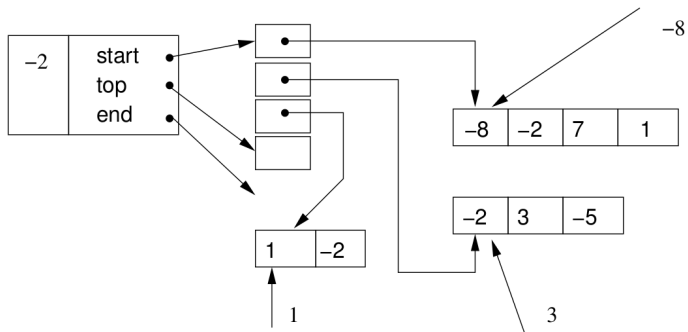
### Advantages

- visit less clauses: when  $x_i = T$  is added only visit clauses where  $\bar{x}_i$  is watched
- no need to do anything at backtracking and restarts
  - watched literals cannot become false



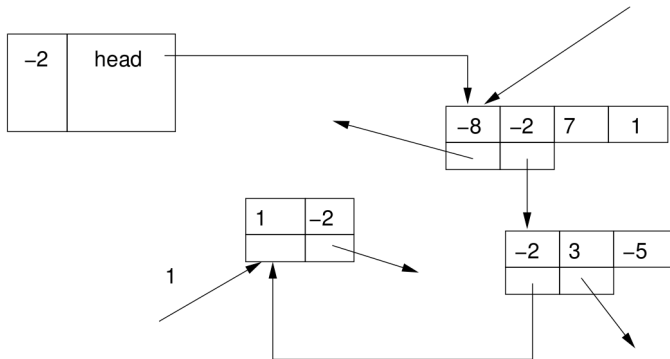


- Good for parallel SAT solvers with shared clause database

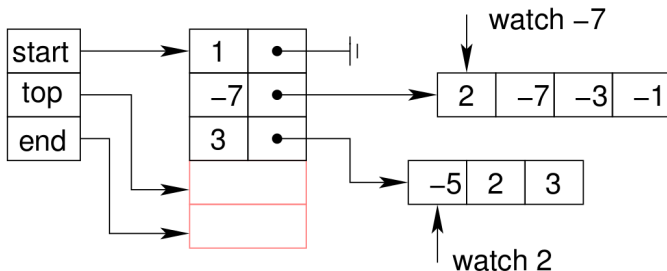


invariant: first two literals are watched





invariant: first two literals are watched



- often the other watched literal satisfies the clause
- for binary clauses no need to store the clause